

ภาคีผนวก

โปรแกรม MATLAB ที่ใช้ในการวิเคราะห์

(ก) ฟังก์ชันของสัญญาณทดสอบ

ก.1 โปรแกรมหลัก

```
gam=8; N=2^gam; n=0:1:N-1; s=fix(N/6)+5; p=fix(N/4)+3; k=fix(N/20)+3; phi=pi/4.3;
f=3*realdisgatom(s,p,k,phi,N,n); %function sample #1
f=f+4*realdisgatom(s+1, p+fix(N/2),k+2,phi,N,n);
f(100:110)=f(100:110)+1;
f=2*sin(2*pi*k/N*n + phi); %function sample #2
f=2*(sin(2*pi*k/N*n + phi)).*(n<(N/2)); %function sample #3
f=zeros(1,N); f(100:150)=2.3;
```

ก.2 โปรแกรมย่อย

```
function turn=realdisgatom(s,p,k,phi,N,n) %real discrete time-frequency atom in eq.(113)
    g=(exp(i*phi))*cpxdisgatom(s,p,k,N,n);
    g=g+(exp(-i*phi))*cpxdisgatom(s,p,-k,N,n);
    turn=kgp(s,p,k,phi,N,n)*g/2;
```

```
function turn=kgp(s,p,k,phi,N,n); %calculate the normalize constant of eq(114)
    gp=cpxdisgatom(s,p,k,N,n);
    gn=cpxdisgatom(s,p,-k,N,n);
    inner=gp*gn'; %when transpose it also make conjugation
    r=real((exp(i*2*phi))*inner);
    turn=sqrt(2)/sqrt(1+r);
```

```
function turn=cpxdisgatom(s,p,k,N,n) %discrete complex Gabor atom in eq.(64)
    turn=pegwin(s,N,(n-p)).*exp(i*2*pi*k*n/N);
```

```
function turn=pegwin(s,N,n); %discrete periodic Gaussian window
    gs=0; count=round(s/(N-1))+1;
```

```

for a=-count:1:count
    gs=gs+gwin((n-a*N)/s);
end
%test for no periodize gs=gwin(n/s);
gs=gs/sqrt(s); %normalize to unit norm
Ks=sum(gs.^2); turn=gs/sqrt(Ks);

```

```

function turn = gwin(t) %Gaussian window g(t) = 21/2 e(- pi t2)
turn = (2(1/4))*exp(-pi*t.^2);

```

(ข) โปรแกรมการวิเคราะห์สัญญาณเสียงต้นหัวใจด้วยวิธีการแม็ซซิงเพ็ชชุก

ข.1 โปรแกรมหลัก

```

clear, close all
% plotted curve color
color=['b' 'g' 'm' 'y' 'r' 'c' 'k']; % k = black colour
%-----
% Read and select PCG
[y,fs]=wavread('C:\MATLAB6p1\work\2546\HSound\3Com_9July\Late Systolic Murmur');
fprintf('\n\t the sapling frequency record = %d\n',fs);
plot(y),grid,...
title('PCG recording (save figure & please ENTER)'),xlabel('samples')
pause,close all
Y=y;
% when,...
% Amplitude value of y in range [-1,+1],signal .wav
% fs is the sample rate in Hertz
% nbits is the number of bits per sample
%-----
% Zoom PCG signal if it's very much data
if fs>11025
    fprintf('\n\t Very much data,please select the data interval for REZOOM\n')
    pause(2)

```

```

    Y=selectpcg(Y,fs);
    figure,...
        plot(Y),grid,...
        title('REZOOM pcg signal (save figure & please ENTER)')
        pause,close all
end    %if fs>11025
%-----
% calculate data decimation factor
df=fix(fs/2640);
fprintf('\n\t the factor of data decimation = %d ,please select ONE cardiac cycle\n',df);
[f,N]=redsamp(Y,fs,df);
newfs=fs/df;
T=1/newfs;
n=0:N-1;
%-----
% plot the selected PCG,to analysis
figure,...
    plot(n*T,real(f)),grid,...
    xlabel('time(sec)'),title('Signal for analysis,decimation PCG')
figure,...
    plot(n,real(f)),grid,...
    xlabel('samples'),title('Signal for analysis,decimation PCG')

pause
tic    % starts a stopwatch timer.
%-----
Rf=f;
f=Rf;
close all
%-----
% variables in used
decomp=[];    % decompose signal
projsig=[];
nrmse=disp=[];    % display 'nrmse' (Error) in percent
resig=0;    % for reconstruction signal,it's not include the residue

```

```

error=5;                % minimum 'nrmse' requirement in Percent
nrmse=100;              % check for iteration process
iter=0;                 % counting for the iteration
loop=1;                 % counting for the color setting

%-----
% matching pursuit method
while nrmse>error %for ii=1:endproj %while normRf>Rm
    iter=iter+1;
    figure(1),...
        hold on,grid on,...
        plot(n,Rf,color(loop)),pause(2)

% search atoms by newton.m
[g,newtdisp,x,phii]=newton(Rf,n,N);
s=x(1); p=x(2); k=x(3);
coef=Rf*g';
proj=(coef)*g;          % <f,g>=(f*g')=coefficeint
Rf=Rf-proj;
projsig=[projsig proj];
decomp=[decomp;coef s p k phii];

plot(n,proj,[color(loop) '+-'],pause(2)
loop=loop+1;
if loop==8              % couting for colour setting
    loop=1;
end                    %if loop==

% find NRMSE (Normalized root-mean-square error)
resig=resig+proj;      % use for checking
e=f-resig;
nrmse=100*sqrt(sum(e.^2)/sum(f.^2)); % reconstruct signal = e
nrmsedisp=[nrmsedisp;nrmse];

% Show Newton result

```

```

fprintf('\n\t-->newton found # %d\n',iter)
fprintf('\n\tM Loop \t |<f,g>| \t s \t p \t tk \t phase\t |grad|\n\n')
disp(newtdisp)
fprintf('\t-->NRMSE := %g\n',nrmsse)
normRf=sqrt(sum(Rf.^2));
fprintf('\t-->|Rf| := %g\n',normRf)
end % while

%-----

fprintf('\n\t-->the iteration of searching # %d loops',iter')
fprintf('\n\t-->The Normalized root-mean-square:NRMSE(in Percent)***\n')
disp(nrmsedisp)

%-----

% subplot to decompose signal in figure(2)
fig=2; cc=0; poss=0; str=1; No=8;
a=(length(projsig))/N;
while a>=1
    cc=cc+1;
    poss=poss+1;
    n1=str;
    n2=n1+N-1;
    figure(fig),...
        subplot(No,1,cc),...
            plot(n*T,projsig(n1:n2)),grid,...
            str=poss*N;
    if cc==No
        cc=0;
        fig=fig+1;
    end % if cc==
    a=a-1;
end %while a~=

%-----

% subplot to residue and reconstruct signal
figure,...
    subplot(2,1,1),plot(n*T,Rf,'r'),grid,... % Residual signal

```

```

        subplot(2,1,2),plot(n*T,resig,'k'),grid % Composite signal
    hold off

% compare the original signal ,the reconstruct signal and the residue
    figure,hold on,grid on,...
        plot(f),plot(resig,'+-k'),plot(Rf,'r'),...
        legend('f','reconstruct','Rf'),...
    hold off

%-----
% change discrete to continue parameters [ y=(s,p,(2*pi*k/N)) to y=(s,u,sigma) ]
    disp(['-->found : coff s p k phi']); decomp
    disp(['-->convert to continuous time'])
    disp(['-->coff s u freq phi'])
    decomp(:,4)=decomp(:,4)/(N*T); % CT freq=k/NT
    decomp(:,3)=decomp(:,3)*T ; % CT u=pT
    decomp(:,2)=decomp(:,2)*T % CT s=s*T

%-----
% test wigner distribution
    Resi=decomp;
    MaxFre=1/(2*T)
    tv=n*T;
    fv=0:MaxFre/100:MaxFre;
    [t,freq]=meshgrid(tv,fv);
    [ResiRow,ResiCol]=size(Resi);
    Wg=0;
    for I=1:1:ResiRow;
        Wg=Wg+Resi(I,1)*2*exp(-2*pi*(((t-Resi(I,3))/Resi(I,2)).^2 +(Resi(I,2)*2*pi*(freq-Resi(I,4))/(2*pi)).^2));
    end; %for

% plot 3D
    figure,...
        mesh(t,freq,Wg);

%-----
    time=toc;
    fprintf('-->Total time: %g sec ( %g min )= %g h \n',time,time/60,time/3600); save

```

ข.2 โปรแกรมย่อย

ข.2.1 ฟังก์ชันการกรองและเลือกสัญญาณเสียงต้นหัวใจเพื่อนำมาวิเคราะห์

```
function Y=butterlpf(N,fc,fs,y)      % 8th-order Butterworth Low Pass Filter
% Y=butterlpf(N,fc,fs,y)
% when N:order, fc:cutoff frequency,fs:Sampling rate
% -->return signal to Y
wn=fc/(fs/2);                      % fs = sample rate of signal y
[b,a]=buttr(N,wn);                  % Nth order lowpass digital Butterworth filter
Y=filter(b,a,y);

function Y=selectpcg(y,fs)          % for selection of PCG interval n1:n2
n=0:length(y)-1;    T=1/fs;
figure,...
    plot(n*T,y),grid,...           % Plot Normal Heart sounds
    xlabel('time (second)'),ylabel('Normalized amplitude')
    title('Please select the PCG')
[xin,yin]=ginput(2);              % เลือกช่วงสัญญาณที่จะนำมาวิเคราะห์
n1=fix(fc*xin(1));
n2=fix(fs*xin(2));
Y=y(n1:n2);                       % ได้ช่วงสัญญาณที่จะนำมาวิเคราะห์ ช่วง n1:n2
```

ข.2.2 ฟังก์ชัน Garbor dictionary

```
function g=gausswin59(t)            % g(t) is the Gaussian window function and the continue signal
g=(2^(1/4))*exp(-pi*t.^2);         % t=time

function gs=dsgauss63(s,n,N)        % gs(n) is 'the Discrete Gaussian window function and the discrete signal
% s = scale factor,can only vary between 1 and N
% p = transtation , vary between -a to +a ( in eq.(63)vary between -inf ot +inf)
% N = Sampling Rate or the sample of signal (suppose that signal is real)
% Ks = K = Normalize constant the discrete norm of gs ,||gs(n)||=1
% n = integer
gs=0; a=3;
```



```

    for p=-a:a
        ar=(n-p*N)/s;
        g=gausswin59(ar);
        gs=gs+g;
    end
gs=gs/sqrt(s);
Ks=sqrt(sum(gs.^2));           % Ks is the Normalized constant |gs|=1
gs=gs/Ks;

function gy=CpxGAtom64(s,p,phi,n,N)   % gy(n) is The Discrete Complex Gabor atom
% gy(n)=gs(n-p)exp((2*pi*k*n/N))
% y=(s,p,2*pi*k*n/N)
% s is set of ]1,N[, is not necessary integer
% p(Time-position)and k(Frequency index) are all integer
% N=samples of signal
gs=dscgauss63(s,n-p,N);
gy=gs.*exp(i*phi*n);

function gyr=ReGAtom113(s,p,k,zeta,n,N)   % gyr is 'The Real discrete Time-Frequency atoms'
% gyr = (K/2)[exp(i*zeta)(gy)+exp(-i*zeta)(gy-)]

% y=(s,p,phi), y- = (s,p,-phi), phi=2*pi*k/N
% K=Normalize constant
% gy and gy- = Complex Garbor atoms , eq.(64)
% zeta=phase, [0,2*pi[, the complex phase of <Rf,gy>
phi=2*pi*k/N;
gy=CpxGAtom64(s,p,phi,n,N);
gyneg=CpxGAtom64(s,p,-phi,n,N);

% Compute the Normalize constant K, eq.(114)
inner=gy*gyneg';
inner=(exp(i*2*zeta))*inner;
K=(sqrt(2))/(sqrt(1+real(inner)));
gyr=K*((exp(i*zeta))*gy+(exp(-i*zeta))*gyneg)/2;

```

ข.2.3 ฟังก์ชันการค้นหาคอมพอนเนนต์จากดิกชันนารี

```
function [xo,gyo,inn,jpk]=sampD(f,n,N) %Search for max|<f,g>|, and parameter s,p,k for newton start point
% Sampling dictionary,search in sub-dictionary,in eq.(64)
% sub-dictionary:  $y = (a^j, p[a^j]du, ka^{-j}dc)$ ,  $a=2, du=0.5, dc=\pi$ 
%  $0 < j < \log_2(N), 0 \leq p < N2^{-(j+1)}, 0 \leq k < 2^{-(j+1)}$ 
% From theorem 2:  $y = (a^j, p[a^j]du, ka^{-j}dc)$ , for  $(j,p,k) \in Z^3$ 
%  $du * dc < 2 * \pi$ 
%-----
a=2; du=0.5; dc=pi;      inno=0;
for jj=1:1:fix(log2(N))-1
    s=a^jj;
    for pp=0:1:(N*2^(-jj+1))-1
        p=pp*s*du;
        for kk=0:1:(2^(jj+1))-1
            phi=kk*dc/s;
            gy=CpxGAtom64(s,p,phi,n,N);
            innN=abs(f*gy');
            if innN>inno
                so=s;   po=p;   ko=kk*N/(s*2);
                jpk=[jj;pp;kk];   inno=innN;   gyo=gy;
            end % if innN
        end % for kk
    end % for pp
end % for jj
xo=[so;po;ko];
```

```
function [g,newtdisp,x,phii]=newton(f,n,N) % 1. Search in sub-dictionary by 'sampD.m'
% 2. Refind with a Newton search strategy to recover the time-frequency parameter
% that best match the signal components.
%-----
% Variable for used within function
newtdisp=[]; % display for searching any parameter
newtloop=0; % for counting the newton loop
```

```

del=0.00001;           % used for finding the derivative
kred=[];

%-----
% search atom in sub-dictionary
[xo,gyo,inno,jpk]=sampD(f,n,N);
kred=[kred xo(3)];

% check for |grad| at this point
Dx1=(inner(xo(1)+del,xo(2),xo(3),n,N,f)-inner(xo(1),xo(2),xo(3),n,N,f))/del;
Dx2=(inner(xo(1),xo(2)+del,xo(3),n,N,f)-inner(xo(1),xo(2),xo(3),n,N,f))/del;
Dx3=(inner(xo(1),xo(2),xo(3)+del,n,N,f)-inner(xo(1),xo(2),xo(3),n,N,f))/del;
grado=[Dx1;Dx2;Dx3];
slopeo=abs(sqrt(sum(grado.^2)));
newtdisp=[newtdisp;newtloop inno xo(1) xo(2) xo(3) angle(f*gyo') slopeo];
%-----

% Set boundary for Newton search
J=jpk(1,1); P=jpk(2,1); K=jpk(3,1);
sl=2^(J-1/2); pl=round((P-1)*(2^J)/2); kl=round(N*(K-1)/(2*(2^J)));
sh=2^(J+1/2); ph=round((P+1)*(2^J)/2); kh=round(N*(K+1)/(2*(2^J)));
    if sl<1; sl=1; end
    if sh>N; sh=N; end
    if pl<0; pl=0; end
    if ph>N; ph=N; end
    if kl<0; kl=0; end
    if kh>N; kh=N; end

% display the boudary of s,p,k
fprintf('\n\nthe boundary of s,p,k:\n\n\t J   P   K\n')
disp([J P K])
fprintf('\n\t s   p   k\n')
disp([[sl pl kl];xo';[sh ph kh]])

%-----

% Newton search
x=[xo(1);round(xo(2));round(xo(3))];
error=0.001;           % for check the slope (|grad|) in while loop
slope=1; innl=inno;

```

```

while slope>error                                %for iterate=1:5 %
    newtloop=newtloop+1;
    % find the gradient
    Dx1=(inner(x(1)+del,x(2),x(3),n,N,f)-inner(x(1),x(2),x(3),n,N,f))/del;
    Dx2=(inner(x(1),x(2)+del,x(3),n,N,f)-inner(x(1),x(2),x(3),n,N,f))/del;
    Dx3=(inner(x(1),x(2),x(3)+del,n,N,f)-inner(x(1),x(2),x(3),n,N,f))/del;
    gradn=[Dx1;Dx2;Dx3];
    % find the hessian matrix
    x1=x(1)+del; x2=x(2)+del; x3=x(3)+del;
    H11=(((inner(x1+del,x(2),x(3),n,N,f)-inner(x1,x(2),x(3),n,N,f))/del)-Dx1)/del;
    H12=(((inner(x1,x2,x(3),n,N,f)-inner(x1,x(2),x(3),n,N,f))/del)-Dx2)/del;
    H13=(((inner(x1,x(2),x3,n,N,f)-inner(x1,x(2),x(3),n,N,f))/del)-Dx3)/del;
    H21=(((inner(x1,x2,x(3),n,N,f)-inner(x(1),x2,x(3),n,N,f))/del)-Dx1)/del;
    H22=(((inner(x(1),x2+del,x(3),n,N,f)-inner(x(1),x2,x(3),n,N,f))/del)-Dx2)/del;
    H23=(((inner(x(1),x2,x3,n,N,f)-inner(x(1),x2,x(3),n,N,f))/del)-Dx3)/del;
    H31=(((inner(x1,x(2),x3,n,N,f)-inner(x(1),x(2),x3,n,N,f))/del)-Dx1)/del;
    H32=(((inner(x(1),x2,x3,n,N,f)-inner(x(1),x(2),x3,n,N,f))/del)-Dx2)/del;
    H33=(((inner(x(1),x(2),x3+del,n,N,f)-inner(x(1),x(2),x3,n,N,f))/del)-Dx3)/del;
    H=[H11 H12 H13;H21 H22 H23;H31 H32 H33];
    % find the step newton
    d=-inv(H)*gradn;
    % find next point
    xn=x+d;
    xn(2)=round(xn(2));
    xn(3)=round(xn(3));

    % check for boundary of serching
    scale=10; red=1; intowhile=0;
    if ~isempty(find([(sl<xn(1))&(xn(1)<sh);...
        (pl<=xn(2))&(xn(2)<ph);...
        (kl<=xn(3))&(xn(3)<kh)]==0))
        for q=1:20
            scale=scale-red; dred=d*(scale/10); xn=x+dred;
            xn(2)=round(xn(2)); xn(3)=round(xn(3)); intowhile=1;
            newtdisp=[newtdisp;newtloop 0 xn(1) xn(2) xn(3) 0 q];
        end
    end
end

```

```

        if isempty(find([(sl<xn(1))&(xn(1)<sh);...
            (pl<=xn(2))&(xn(2)<ph);...
            (kl<=xn(3))&(xn(3)<kh)]==0))
            break
        end % if isempty
    end %for q=
end %if ~isempty

if intowhile==1
    d=dred;
    disp([' new s p k'])
    disp(xn')
end %intowhile==

% find complex atom,phii and |<f,gy>|
gy=CpxGAtom64(xn(1),xn(2),2*pi*xn(3)/N,n,N);
phii=angle(f*gy');    inn=abs(f*gy');
if inn<inn1
    redstep=20;
    for trystep=(redstep-1):-1:0
        tryd=d*(trystep/redstep);        xn=x+tryd;
        xn(2)=round(xn(2));        xn(3)=round(xn(3));
        gy=CpxGAtom64(xn(1),xn(2),2*pi*xn(3)/N,n,N);
        phii=angle(f*gy');        inn=abs(f*gy');
        newtdisp=[newtdisp;newtloop inn xn(1) xn(2) xn(3) phii trystep];
        if inn>=inn1
            x=xn;
            break
        end %inn>=
    end %for trystep
else    x=x+d;    x(2)=round(x(2));    x(3)=round(x(3));
end %if inn<

% set k,less than N/2
kred=[kred x(3)];
if x(3)>N/2

```

```

        x(3)=fix(N-x(3));    kred=[kred 4444 x(3)];
        gy=CpxGAtom64(x(1),x(2),2*pi*x(3)/N,n,N);
        phii=angle(f*gy');
    end %if x(3)

Dx1=(inner(x(1)+del,x(2),x(3),n,N,f)-inner(x(1),x(2),x(3),n,N,f))/del;
Dx2=(inner(x(1),x(2)+del,x(3),n,N,f)-inner(x(1),x(2),x(3),n,N,f))/del;
Dx3=(inner(x(1),x(2),x(3)+del,n,N,f)-inner(x(1),x(2),x(3),n,N,f))/del;
grad=[Dx1;Dx2;Dx3];
slope=abs(sqrt(sum(grad.^2)));
newtdisp=[newtdisp;newtloop inn x(1) x(2) x(3) phii slope];

% break if infgNew better infgf less than 0.5%
if abs((inn-inn1)/inn1)<0.0005
    disp('xxxxxxxxxxxxxxxxxxxxxxxxxxxx')
    break
else
    inn1=inn;
end %if abs
end % while error

%-----
% find real atom
g=ReGAtom113(x(1),x(2),x(3),phii,n,N);
% display k
fprintf('\ndisplay k,for k>N/2 or not\n\n')
disp(kred)

function h=inner(x1,x2,x3,n,N,f)    % Use for 3 variables (x1,x2,x3) optimization,Newton's method
% This function is |<f,gy>|,use for Newton search
% gy is Discrete atom in eq.(64)

% create the Complex Gabor atom (Dictionary)
phi=2*pi*x3/N;
gy=CpxGAtom64(x1,x2,phi,n,N);    % Discrete complex atoms in eq.(64)
h=abs(f*gy');    % <f,gy>=sum[(f)(gy*)]
% require h is maximum value,with Newton search

```

ข.2.4 ฟังก์ชันการลดอัตราการสุ่มตัวอย่าง

```

function [f,N]=redsamp(y,fs,df)      % Down the samples by data decimation
    % Butterword LPF:cut off freq.=1kHz,order 8th
    fc=1000;                          % cutoff frequency
    Y=butterlpf(8,fc,fs,y);          % Y is output Butterworth LPF
%-----
    % Select PCG for analysis
    Y=selectpcg(Y,fs);
    fprintf('\n\t Samples of data : %d \n',length(Y))
    n=0:length(Y)-1;    T=1/fs;
    figure,...
        plot(n,real(Y)),grid,...
        xlabel('samples(n)'),title('Before decimating')
    figure,...
        plot(n*T,real(Y)),grid,...
        xlabel('time(second)'),title('Before decimating')
%-----
    % Data decimation of the discrete-time signal
    f=decimate(Y,df);
    fprintf('\n\t Samples of data decimation: %d \n',length(f))
    N=length(f);    n=0:N-1;

```